

# WEST Search History





DATE: Tuesday, September 25, 2007

Hide?	Set Name	Query	Hit Count
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L72	rack\$ and L71	21
<input type="checkbox"/>	L71	l69 and L70	75
<input type="checkbox"/>	L70	sensors or camera\$ and L69	1817332
<input type="checkbox"/>	L69	access point\$ and L68	87
<input type="checkbox"/>	L68	zones and L67	2566
<input type="checkbox"/>	L67	L37 or L66	17933
<input type="checkbox"/>	L66	robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant)	5058
<input type="checkbox"/>	L65	('6711469' '6697709' '6567724' '6505098' '6493606' '6480761' '6330494' '6289265' '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
<input type="checkbox"/>	L64	marc.xa. and legged and inclination	26
<input type="checkbox"/>	L63	marc.xa. and legged and inclinaiton	0
<input type="checkbox"/>	L62	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L61	(edditng or updating) and (motion or traject\$4 or movement) and zmp and robot\$6	17
<input type="checkbox"/>	L60	(edditng or updating) same (motion or traject\$4 or movement) and zmp and robot\$6	8
<input type="checkbox"/>	L59	(edditng or updating) same (motion or traject\$4 or movement) and L58	7
<input type="checkbox"/>	L58	robot and zmp and yaw	129
<input type="checkbox"/>	L57	marc.xa. and zmp	33
<input type="checkbox"/>	L56	10/181500	3
<input type="checkbox"/>	L55	('6697709' '6289265' '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
<input type="checkbox"/>	L54	marc.xa. and robot and zmp	33

<input type="checkbox"/>	L53 (motions or movement or displacement) and L52	92
<input type="checkbox"/>	L52 computer and L51	103
<input type="checkbox"/>	L51 record\$3 and L50	103
<input type="checkbox"/>	L50 (request or command) and L49	124
<input type="checkbox"/>	L49 L45 and L48	129
<input type="checkbox"/>	L48 execut\$5 and L47	247827
<input type="checkbox"/>	L47 run or L45	1224468
	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	99
<input type="checkbox"/>	L46	
<input type="checkbox"/>	L45 (similar or "same") function and L44	152
<input type="checkbox"/>	L44 robot and control software and (chang\$3 or replac\$5)	1753
<input type="checkbox"/>	L43 ('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L42 (10/126774   10/970977   10/935607   10/919172   10/775845   10/732446   10/726597   10/683496   10/637890)	17
<input type="checkbox"/>	L41 (motion or displacement or trajector\$3) and L40	100
<input type="checkbox"/>	L40 (humanoid or two legged robot and human like robot) and zmp and comput\$5	103
<input type="checkbox"/>	L39 robot\$4 and L38	2
<input type="checkbox"/>	L38 HVAC and control and L37	281
	(700/276   700/214   700/215   700/245   700/255   700/246   700/247   700/248   700/249   700/254   700/258   700/259   700/260   700/261 or 340/524   340/501   340/506   340/584 or 701/301 or 901/3   901/46   901/47 or 318/567   318/568.1 or 408/197 or 62/97 or 250/302).ccls.	13206
<input type="checkbox"/>	L37	
<input type="checkbox"/>	L36 L27 and environmental	1009
<input type="checkbox"/>	L35 ('6816332'   '6671580'   '6609046'   '6438459'   '6351685'   '5237468')!.ABPN1,NRPN,PN,TBAN,WKU.	13
	storage cell and storage library and (remov\$4 or attach\$3 or	

<input type="checkbox"/>	L34 detach\$3)	254
<input type="checkbox"/>	L33 ('6691001'  '6535792'  '6480759'  '6327519'  '6304798')!.ABPN1,NRPN,PN,TBAN,WKU.	10
<input type="checkbox"/>	L32 marc.xa. and storage library	21
<input type="checkbox"/>	L31 arm and L30	49
<input type="checkbox"/>	L30 select\$3 and point and L29	185
<input type="checkbox"/>	L29 L27 and travel	203
<input type="checkbox"/>	L28 L27 and rail	29
<input type="checkbox"/>	L27 library same root\$6	2686
<input type="checkbox"/>	L26 storage library same root\$6	3
<input type="checkbox"/>	L25 storage library root\$6	0
<input type="checkbox"/>	L24 storage library and root\$6	64
<input type="checkbox"/>	L23 ('5163001'  '5023790')!.ABPN1,NRPN,PN,TBAN,WKU.	4
<input type="checkbox"/>	L22 air conditioning and robot\$6 and manager	93
<input type="checkbox"/>	L21 air conditioning and robot and manager	47
<input type="checkbox"/>	L20 air conditioning and robot and energy manager	2
<input type="checkbox"/>	L19 air conditioning and robot and energy manager and control\$4	2
<input type="checkbox"/>	L18 air conditioning and robot and energy manager and autonomous and control\$4	1
<input type="checkbox"/>	L17 air conditioning and robot and energy manager and semi autonomous and control\$4	1
<input type="checkbox"/>	L16 air conditioning and robot and energy manager and propelling and control\$4	2
<input type="checkbox"/>	L15 L14	8
<input type="checkbox"/>	L14 10/639428	8
<input type="checkbox"/>	L13 10/639428	8
<input type="checkbox"/>	L12 10/303761 or 10/351427	31
<input type="checkbox"/>	L11 station and L10	129
<input type="checkbox"/>	L10 robots and sens\$3 and L9	464
<input type="checkbox"/>	L9 (700/248   318/568.16   901/246).cccls.	655
<input type="checkbox"/>	L8 10/299047	2
<input type="checkbox"/>	L7 10299047	4

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ*

<input type="checkbox"/>	L6	10/229407	6
<input type="checkbox"/>	L5	10/299407	2
	<i>DB=USPT; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L4	10/299407	1
	<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L3	camera and L2	20
<input type="checkbox"/>	L2	robot\$4 and sensor\$ and condition and L1	59
<input type="checkbox"/>	L1	(SHARMA or BASH or PATEL or JANAKIRAMAN).in.	22777

END OF SEARCH HISTORY